### Real-time synthetic tracking for NEA discovery

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Methods and results

Conclusion and outro

### Who we are?

#### ParaSOL project (UEFISCDI funding) under EURONEAR



- Research network in NEA discovery
- Collaborators in many european countries (and Chile)
- Umbrella: Stănescu and Văduvescu 2021 [1]

- ParaSOL: UEFISCDI-funded project to complete the suite
- Reference blink pipeline
- STU (Synthetic Tracking on Umbrella)
- ► IPP (Image Processing Pipeline)
- ► Webrella

# Synthetic Tracking with STU

- Modern computers feature increasing compute power
- Gains particularly in "accelerator" hardware: GPUs
- Synthetic Tracking [2][3][4][5]: improve SNR by stacking across all possible motion vectors
- Portable: .NET Framework (Linux, Windows maybe others) + OpenCL



## Runtime

- Real-time synthetic tracking
- Example: Wide Field Camera on Isaac Newton Telescope
- 4 CCDs of 9 Mpx each,  $0.33'' \text{ px}^{-1}$
- Readout 30 s, exposure 30 s, total 1 min cadence
- ► Search cone of 10 " min<sup>-1</sup>, stack of 12 images.
- ▶ Runtime: 26 s per CCD, with 2 s for actual ST scan
- ► ST (2 min) ≪ acquisition time (12 min)

## Validation

- ► Tested on telescopes: TCS, INT, T025; over 100000 images in total
- Detected all objects in the TCS dataset that have no pre-processing issues
- ▶ Bulk detection rate on INT WFC of 50%
- ► Validated real-time processing on 3 nights of INT observations

## The good

- Real-time synthetic tracking for the masses
- All objects detected when input images are free of defects
- Validated against a large dataset
- End-to-end pipeline available
- Theoretical model for tuning the detection threshold

## The dangerous

Methods and results

Object Designation	Year Range	Potential Impacts	Impact Probability (cumulative)	<ul> <li>V<sub>infinity</sub> (km/s)</li> </ul>	0 H (mag)	Estima Diama (km	ited Palermo iter ( Scale ) (cum.)	Palermo Scale (max.)	torino
	2026-2121	123		7.35	23.9	0.0	156 -1.16	-1.17	1
101955 Bennu (1999 RQ36)	2178-2290	157	5.7e-4	5.99	20.6	0.4	190 -1.41	-1.59	
29075 (1950 DA)	2880-2880	1	2.96-5	14.10	17.9	1.3	-2.05	-2.05	



Figure: **2023 DW**, follow-up on 1st of March. Detection as reported by STU, from the observation archive. Detection stamp from trimmed mean of 4 images with stars masked, width 300px. Figure: **2023 DZ2**, detected on 27th of February. Detection as reported by STU, with reporting stage re-ran for press release. Detection stamp from mean of 4 input images, width 500px.  $\underset{OOO}{\text{Methods and results}}$ 

#### Next steps

#### Current activities

- Improving reporting and validation
- Decreasing image pre-processing (IPP) runtime
- Continue validation efforts on corner cases

#### Planned activities

- Acquiring and validating on space debris dataset
- Improving handling of many-chip cameras
- Moving other expensive operations to GPU and eliminating processing bottlenecks

Intro 0 Methods and results

Conclusion and outro  $000 \bullet$ 



Question time

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